



Tracking and Data Fusion: A Handbook of Algorithms

Yaakov Bar-Shalom, Peter K. Willett, Xin Tian

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This book, which is the

revised version of the 1995 text

MULTITARGET-MULTISENSOR

TRACKING: PRINCIPLES AND TECHNIQUES, at double the length, is the

most

comprehensive state of the art compilation of practical

algorithms for the estimation of the states of

targets in surveillance systems operating in a

multitarget environment using data fusion.

This problem

is characterized by measurement origin uncertainty,

typical for low observables.

The tools for design of algorithms for the association of

measurements and tracking are presented. Explicit

consideration is given for measurements

obtained from different sensors under realistic

assumptions --- lack of synchronicity and

different detection and accuracy characteristics. Several

real-data examples are given to illustrate

the techniques discussed.

The modeling accounts for target maneuvers, non-unity detection probability,

false alarms, interference from other targets and the finite

resolution capability of sensors. The problems of track initiation,

maintenance and multisensor data fusion are considered. The

optimization of certain signal processing parameters based on

tracking performance is also discussed. The latest results on measurement extraction for unresolved targets,

sensor management and data fusion are included.

Many of these techniques have applications to state estimation when using

multiple sensors in control systems, autonomous vehicle navigation, robotics and wireless communication.

An extensive index is provided with all the indexed terms highlighted in the text for the convenience of the

reader.

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